Time-Delay Interferometry

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• Reminder of what LISA is and what the main noise sources are

• Why conventional laser noise cancellation method won't work for LISA

• Time-Delay-Interferometry
  • View unequal arm LISA as symmetric system of one-way links
  • Exploit transfer function of signals and noises to construct TDI- observables which cancel the leading noises while keeping GW signals
  • Derive basis functions for cancellation of principal noises (X, Y, Z), (α,β,γ), ζ, etc.

• Applications of TDI
  • LISA sensitivities to periodic waves
  • On-orbit instrumental noise calibration and isolation of GW background

• Practical Problems
References

For LISA configuration, orbits, and noises:


Folkner, W. et al. 1997 Classical Quantum Grav. 14, 1543

Ph237b talks by William Folkner, Robert Spero, Bonny Schumaker  http://elmer.tapir.caltech.edu/ph237

For TDI:


Dhurandhar, S., Nayak, K., and Vinet, J-Y, gr-cq/0112059, 22 December 2001
LISA and Its Main Noise Sources

- GW detector in the LF (~millihertz) band with expected sensitivity to periodic waves $\sim 10^{-23}$ in a one year integration

- 3 spacecraft, six lasers, six optical benches, 3 USOs; nominally equilateral triangle (time-variable arm lengths with $\delta L/L \sim 2\%$ and $L \approx 5 \times 10^9$ meters),

- Laser signals exchanged between spacecraft pairs

- Nominal noise spectra (one-sided)

  - Raw laser phase noise: $30 \text{ Hz Hz}^{-1/2}$ $\Rightarrow S_y(f) = 10^{-26} \text{ Hz}^{-1}$
  - Optical path noise: $20 \times 10^{-12} \text{ m Hz}^{-1/2}$ $\Rightarrow S_y(f) = 1.8 \times 10^{-37} (f/1 \text{ Hz})^2 \text{ Hz}^{-1}$
  - Optical bench noise: $10 \times 10^{-9} \text{ m Hz}^{-1/2}$ $\Rightarrow S_y(f) = 4.4 \times 10^{-32} (f/1 \text{ Hz})^2 \text{ Hz}^{-1}$
  - Proof-mass noise: $3 \times 10^{-15} \text{ m/sec}^2 \text{ Hz}^{-1/2}$ $\Rightarrow S_y(f) = 2.5 \times 10^{-48} (f/1 \text{ Hz})^{-2} \text{ Hz}^{-1}$
Mission Concept
Spacecraft Formation

- Three spacecraft in triangular formation; separated by 5 million km
- Spacecraft have constant solar illumination; payload shielded from sunlight
- Formation trails Earth by 20°; compromise constant arm-lengths vs cost
Spacecraft Orbits

- Spacecraft orbits evolve under gravitational forces only
- Spacecraft fly “drag-free” to shield proof masses from non-gravitational forces
Arm Length Change and Doppler Shift

![Graph showing Arm Length Change and Doppler Shift over time. The graph plots Arm Length (km) and Rate of change (m/s) against Time (yrs). The data includes points at 4.90 \times 10^6, 4.95 \times 10^6, 5.00 \times 10^6, 5.05 \times 10^6, and 5.10 \times 10^6.](image-url)
Why Consider Alternatives to Conventional Michelson Interferometry?

• In equal-arm interferometer, laser signal experiences same delay in each arm—when signals from the two arms are combined at the detector any instability in the laser light is common and cancels exactly

• Because of orbital dynamics, however, LISA will necessarily have unequal and time-variable arms lengths

• In unequal arm length cases, signals from each arm return at different times. Straightforward differencing will then not cancel laser noise exactly. If ε is the fractional arm-length imbalance

\[ C(t - 2 L_1) - C(t - 2 L_2) \approx 2 \varepsilon L_1 \frac{dC}{dt} \]

• Magnitude of the effect is huge: for ε L_1 = 2% arm length difference and nominal stability of lasers, imprecise phase noise cancellation introduces residual noise orders of magnitude larger than the desired GW signal sensitivity
Unequal Arm Michelson Interferometry

• Consider a one-bounce, unequal arm transponding Michelson interferometer

• Measure phase difference between transmitted and received signals in each arm separately, then combine data in post-processing to cancel the laser noise

• If $\phi_i$ is the phase difference in the arm $i$ ($i=1,2$) then the data combination

$$[ \phi_1(t - 2L_2/c) - \phi_1(t) ] - [\phi_2(t - 2L_1/c) - \phi_2(t) ]$$

cancels the phase noise, retaining the gravity wave

• Tolerance on arm length knowledge can be determined by requirement that imperfection in laser noise cancellation be no worse than the uncancelled noises (e.g. shot noise). For nominal LISA parameters, this means the arms must be known to about 30 meters.

laser noise

shot noise
time-domain cancelled

simulated signal

$\log_{10}(S_f (\text{Hz}^{-1}))$

$\log_{10}(\text{Fourier frequency, Hz})$
The Main Ideas

• LISA's can be analyzed symmetrically in terms of Doppler shifts on 6 one-way laser links connecting 6 optical benches on the three spacecraft

• Time-Delay interferometry = methods to cancel principal noises by time-shifting/adding data from single laser links, while retaining the signal

• Use linear systems ideas to build up aggregate GW signal and aggregate instrumental noise for each data combination

• Multiple noise-canceling data streams can be formed simultaneously; robustness against some classes of subsystem failure

• Applications
  • On-orbit noise calibration/isolation of confusion-limited GW background
  • Sensitivity computations
  • Simulations of what the LISA time series will look like (e.g. bursts)
One-Way Links: GW Response

- Notation and conventions:
  - Three LISA spacecraft, equidistant from point "O"
  - Unit vectors $p_i$ locate the spacecraft in the plane; $\mu_i = k \cdot p_i$
  - Unit vectors $n_i$ connect spacecraft pairs with the indicated orientation
  - $y_{21} = \Delta v/v_o$ is fractional Doppler shift on link originating at s/c 3, measured at s/c 1; $y_{31}$ is fractional Doppler shift on link originating at s/c 2, measured at s/c 1
  - Cyclic permutation of the indices (1 $\rightarrow$ 2 $\rightarrow$ 3 $\rightarrow$ 1) for the other $y_{ij}$

- GW response is "two-pulse" (Wahlquist, GRG, 19, 1101, 1987), e.g.:

$$y_{21}(t) = \left[1 - \frac{\ell}{L_2}(\mu_3 - \mu_1)\right]\left[\Psi_2(t-L_3-\mu_3\ell) - \Psi_2(t-\mu_1\ell)\right]$$

$$\Psi_i(t) = \frac{1}{2} \frac{n_i \cdot h(t) \cdot n_i}{1-(k \cdot n_i)^2}$$
to s/c 2

$\hat{n}_3$

to s/c 3

$\hat{n}_2$
One-Way Links: Noise Response

- Doppler link noises, in simplest case:

  laser phase noise: \( y_{31} = C_2^*(t - L_3) - C_1(t) = C_{2,3}^* - C_1 \)

  shot noise: \( y_{31} = \text{shot}_{31}(t) \)

  optical bench and proof mass noise:

  \[ y_{31} = n_3 \cdot V_2^*(t - L_3) - 2 n_3 \cdot v_1(t) + n_3 \cdot V_1(t) \]

  metrology data:

  \[ z_{31} = C_1^*(t) - 2 n_2 \cdot (v_1^* - V_1^*) + \eta - C_1(t) \]

- Introduced comma-notation, e.g. \( C_2(t - L_3) = C_{2,3} \)

- \( C_i \)'s, \( V_i \)'s, \( v_i \)'s, shot, etc. are random variables; ensemble average of squared Fourier transforms of time-domain transfer functions gives spectral modulation
Assume unequal, but at this point not time-varying, armlengths and that the lasers all have the same center frequency. Forming, for example,

\[
\alpha_{\text{gen}} = y_{21} - y_{31} + y_{13,2} - y_{12,3} + y_{32,12} - y_{23,13} + \frac{1}{2} [z_{13,2} + z_{13,13} + z_{21} + z_{21,123} + z_{32,3} + z_{32,12}] + \frac{1}{2} [z_{23,2} + z_{23,13} + z_{31} + z_{31,123} + z_{12,3} + z_{12,12}]
\]

exactly cancels all laser phase (\(C_i\) and \(C_i^*\)) and optical bench (\(V_i\) and \(V_i^*\)) noise. Of course non-inertial motion of the proof masses do not cancel:

proof mass noise for \(\alpha_{\text{gen}} = \)
\n\[
\begin{align*}
& n_1 \cdot (v_{2,3} - v_{2,12} + v_{3,2}^* - v_{3,13}^*) + \\
& n_2 \cdot (v_{3,13} - v_{3,2} + v_{1}^* - v_{1,123}^*) + \\
& n_3 \cdot (v_{1} - v_{1,123} + v_{2,12}^* - v_{2,3}^*)
\end{align*}
\]
UNEQUAL-ARM LENGTH INTERFEROMETRIC COMBINATIONS (X,Y,Z)

The unequal-arm length interferometric combinations are (X,Y,Z):

\[
X = y_{32,322} - y_{23,233} + y_{31,22} - y_{21,33} + y_{23,2} - y_{32,3} + y_{21} - y_{31} \nonumber
+\frac{1}{2}(-z_{21,2233} + z_{21,33} + z_{21,22} - z_{21}) \nonumber
+\frac{1}{2}(+z_{31,2233} - z_{31,33} - z_{31,22} + z_{31}).
\]

(1)

Combinations Y and Z are given by cyclic permutation of the indices in X. The gravitational wave signal maps to X as a superposition of eight realizations

\[
X^{gw} = \left[1 - \frac{l}{L_3}(\mu_1 - \mu_2)\right] (\Psi_3(t - \mu_1 l - 2L_3 - 2L_2) - \Psi_3(t - \mu_2 l - L_3 - 2L_2)) - \left[1 + \frac{l}{L_2}(\mu_3 - \mu_1)\right] (\Psi_2(t - \mu_1 l - 2L_2 - 2L_3) - \Psi_2(t - \mu_3 l - L_2 - 2L_3)) + \left[1 + \frac{l}{L_3}(\mu_1 - \mu_2)\right] (\Psi_3(t - \mu_2 l - L_3 - 2L_2) - \Psi_3(t - \mu_1 l - 2L_2)) - \left[1 - \frac{l}{L_2}(\mu_3 - \mu_1)\right] (\Psi_2(t - \mu_3 l - L_2 - 2L_3) - \Psi_2(t - \mu_1 l - 2L_3)) + \left[1 + \frac{l}{L_2}(\mu_3 - \mu_1)\right] (\Psi_2(t - \mu_1 l - 2L_2) - \Psi_2(t - \mu_3 l - L_2)) - \left[1 - \frac{l}{L_3}(\mu_1 - \mu_2)\right] (\Psi_3(t - \mu_1 l - 2L_3) - \Psi_3(t - \mu_2 l - L_3)) + \left[1 - \frac{l}{L_2}(\mu_3 - \mu_1)\right] (\Psi_2(t - \mu_3 l - L_2) - \Psi_2(t - \mu_1 l)) - \left[1 + \frac{l}{L_3}(\mu_1 - \mu_2)\right] (\Psi_3(t - \mu_2 l - L_3) - \Psi_3(t - \mu_1 l)),
\]

(2)

A \(\delta\)-function GW signal would produce eight pulses in X, at times depending on the arrival direction of the wave and the detector configuration: \(\mu_1 l\), \(\mu_2 l + L_3\), \(\mu_3 l + L_2\), \(\mu_1 l + 2L_3\), \(\mu_1 l + 2L_2\), \(\mu_3 l + L_2 + 2L_3\), \(\mu_2 l + 2L_2 + L_3\), and \(\mu_1 l + 2L_2 + 2L_3\).
NOISE IN (X,Y,Z)

The noise in X due to proof-mass motions, $\bar{v}_i$ and $\bar{v}_i^*$, is

$$X^{\text{proof mass}} = \hat{n}_2 \cdot (-\bar{v}_{1,2233}^* + \bar{v}_{1,22}^* - \bar{v}_{1,33}^* + \bar{v}_1^* + 2\bar{v}_{3,233}^* - 2\bar{v}_{3,2})$$

$$+ \hat{n}_3 \cdot (-\bar{v}_{1,2233} + \bar{v}_{1,33} - \bar{v}_{1,22} + \bar{v}_1 + 2\bar{v}_{2,233}^* - 2\bar{v}_{2,3}^*), \quad (3)$$

while the optical path noises (shot and beam pointing noises) affecting the measurements $y_{ij}$, enter into the interferometric combination X as follows

$$X^{\text{optical path}} = n_{32,22} - n_{23,3} + n_{31,2} - n_{21,3} + n_{23,2} - n_{32,3} + n_{21} - n_{31}. \quad (4)$$

Here $n_{ij}$ are the random processes associated with the optical path noises affecting the Doppler measurements $y_{ij}$.

The power spectra of the acceleration and optical path noise components of X, assuming independent individual proof mass acceleration noises, (with equal raw spectra) and independent optical path noises (with equal raw spectra) and for the equilateral triangle ($L_1 = L_2 = L_3 = L$) case

$$S_X = [8\sin^2(4\pi f L) + 32\sin^2(2\pi f L)]S_y^{\text{proof mass}} + 16\sin^2(2\pi f L) S_y^{\text{optical path}}. \quad (5)$$
FULLY SYMMETRIC (SAGNAC) COMBINATION, $\zeta$

Another combination of all six data streams which exactly cancels all laser and optical bench motion noises and has the property that each of the $y_{ij}$ enters exactly once and is lagged by exactly one of the one-way light times is $\zeta$

\[
\zeta = y_{32,2} - y_{23,3} + y_{13,3} - y_{31,1} + y_{21,1} - y_{12,2} \\
+ \frac{1}{2} (-z_{13,21} + z_{23,12} - z_{21,23} + z_{31,23} - z_{32,13} + z_{12,13}) \\
+ \frac{1}{2} (-z_{32,2} + z_{12,2} - z_{13,3} + z_{23,3} - z_{21,1} + z_{31,1}).
\] (11)

Like $\alpha$, $\beta$, $\gamma$, this combination also has a six-pulse response to gravitational radiation

\[
\zeta^{gw} = \left[ 1 - \frac{l}{L_3}(\mu_1 - \mu_2) \right] (\Psi_3(t - \mu_1 l - L_3 - L_2) - \Psi_3(t - \mu_2 l - L_2)) \\
- \left[ 1 + \frac{l}{L_2}(\mu_3 - \mu_1) \right] (\Psi_2(t - \mu_1 l - L_2 - L_3) - \Psi_2(t - \mu_3 l - L_3)) \\
+ \left[ 1 - \frac{l}{L_1}(\mu_2 - \mu_3) \right] (\Psi_1(t - \mu_2 l - L_1 - L_3) - \Psi_1(t - \mu_3 l - L_3)) \\
- \left[ 1 + \frac{l}{L_3}(\mu_1 - \mu_2) \right] (\Psi_3(t - \mu_2 l - L_3 - L_1) - \Psi_3(t - \mu_1 l - L_1)) \\
+ \left[ 1 - \frac{l}{L_2}(\mu_3 - \mu_1) \right] (\Psi_2(t - \mu_3 l - L_2 - L_1) - \Psi_2(t - \mu_1 l - L_1)) \\
- \left[ 1 + \frac{l}{L_1}(\mu_2 - \mu_3) \right] (\Psi_1(t - \mu_3 l - L_1 - L_2) - \Psi_1(t - \mu_2 l - L_2)).
\] (12)

A $\delta$-function GW signal would produce six pulses in $\zeta$, located at: $\mu_1 l + L_3 + L_2$, $\mu_2 l + L_1 + L_3$, $\mu_3 l + L_1 + L_2$, $\mu_3 l + L_3$, $\mu_2 l + L_2$, and $\mu_1 l + L_1$. 
NOISE IN $\zeta$

The proof-mass noise for $\zeta$ is

$$\zeta^{\text{proof mass}} = \hat{n}_1 \cdot (\vec{v}_{2,2} - \vec{v}_{2,13} + \vec{v}_{3,3}^* - \vec{v}_{3,21}^*)$$

$$+ \hat{n}_2 \cdot (\vec{v}_{3,3} - \vec{v}_{3,21} + \vec{v}_{1,1}^* - \vec{v}_{1,23}^*)$$

$$+ \hat{n}_3 \cdot (\vec{v}_{1,1} - \vec{v}_{1,23} + \vec{v}_{2,2}^* - \vec{v}_{2,13}^*) ,$$

(13)

while the contribution from the optical path noise is

$$\zeta^{\text{optical path}} = n_{32,2} - n_{23,3} + n_{13,3} - n_{31,1} + n_{21,1} - n_{12,2} .$$

(14)

The power spectra of the acceleration and optical path noise components of $\zeta$, assuming equal and independent individual proof mass acceleration noises, equal and independent optical path noises, and the equilateral triangle configuration are

$$S_{\zeta} = 24 \sin^2(\pi f L) \; S_y^{\text{proof mass}} + 6 \; S_y^{\text{optical path}} .$$

(15)
Noise-Canceling Data Combinations: Spectral Modulation of Noise

• If all proof-masses are independent and have same spectrum, and for the LISA equilateral case, ensemble average of FT-squared gives spectral modulation for \( \alpha \)'s proof mass noise:

\[
[8 \sin^2(3 \pi f L) + 16 \sin^2(\pi f L)] S_{\text{proof mass}}
\]

• Similar argument gives proof mass noise for other combinations:

  • for Michelson interferometer (X):

\[
[8 \sin^2(4 \pi f L) + 32 \sin^2(2 \pi f L)] S_{\text{proof mass}}
\]

  • for Sagnac combination (\( \zeta \)):

\[
[24 \sin^2(\pi f L)] S_{\text{proof mass}}
\]

• and so forth for other combinations and for optical path noise...
The various data combinations here are not unique. They span a space of data combinations which cancel the principal noises. In this Appendix, we summarize the relationships between the various laser- and optical-bench-motion-noise canceling data combinations.

\[
\zeta - \zeta_{,123} = \alpha_{,1} - \alpha_{,23} + \beta_{,2} - \beta_{,31} + \gamma_{,3} - \gamma_{,12} \tag{28}
\]

In each of the following, two more relationships can be obtained by cyclic index permutation:

\[
X_{,1} = \alpha_{,32} - \beta_{,2} - \gamma_{,3} + \zeta \tag{29}
\]

\[
E = \alpha - \zeta_{,1} \tag{30}
\]

\[
U = \gamma_{,1} - \beta \tag{31}
\]

\[
P = \zeta - \alpha_{,1} \tag{32}
\]
Time-Delay Interferometry

- LISA's can be analyzed symmetrically in terms of Doppler shifts on 6 one-way laser links connecting 6 optical benches on the three spacecraft + metrology time series comparing the lasers and relative optical bench motions within the 3 spacecraft.

- Time-Delay interferometry = methods to cancel principal noises by time-shifting/adding data from single laser links, while retaining the signal.

- The functional space of noise-canceling TDI-combinations is 3-dimensional:

\[
\xi - \xi_{123} = \alpha_{,1} - \alpha_{,23} + \beta_{,2} - \beta_{,31} + \gamma_{,3} - \gamma_{,12}
\]

\[
X_{,1} = \alpha_{,32} - \beta_{,2} - \gamma_{,3} + \xi
\]

- One TDI-combination, \( \xi \), is sensitive to proof-mass and optical path noises, but relatively insensitive to GW at low Fourier frequencies.

- Many TDI-combinations can be formed simultaneously.
Application of TDI: Sensitivity Calculations

• Conventional figure-of-merit is RMS sensitivity required for a sinusoidal wave as a function of Fourier frequency

  • SNR = 5 in bandwidth B = 1/(one year)
  
  • Averaged over source position and over wave polarization state

\[ h = \frac{\text{noise}(f)}{\text{signal}(f)} = \frac{5 \sqrt{S_{\text{noise}}(f) B}}{\text{rms GW response}(f)} \]

• Thus need GW signal response for a given noise-canceling data combination and the noise spectra (including transfer functions for both signal and noise) for that data combination
Procedure: GW Signal

For a given noise-canceling TDI combination (e.g. \(\alpha, X, P\), etc) and for each Fourier frequency in the band:

- Generate N "sources", uniform on the celestial sphere, radiating GWs with random, general elliptical polarization state (uniform on the Poincare sphere)—4 numbers: "right ascension", "declination", wave ellipticity, and wave tilt
- Generate \(\Psi_i\) (which depend on the s/c positions, gravitational wave vector and the polarization state)
- Compute the \(y_{ij}\) (which depend on the \(\Psi_i\), wavevector, arm lengths, and array orientation w.r.t. the source \([p_i]\))
- Form desired TDI combination of \(y_{ij}\) canceling laser/optical bench noises (if in long-wavelength limit, check calculation against LWL analytical expansion)
- Iterate over the N Monte Carlo sources/polarizations to compute the mean-square GW signal response for this data combination at this frequency
- Step to next frequency

- Examples follow
\[ \alpha^{gw} \rightarrow (1/2)L_1(L_2 - L_3) \mathbf{n}_1 \cdot \mathbf{h}'' \cdot \mathbf{n}_1 \]
\[ - (1/2)L_2(L_1 + L_3) \mathbf{n}_2 \cdot \mathbf{h}'' \cdot \mathbf{n}_2 \]
\[ + (1/2)L_3(L_2 + L_1) \mathbf{n}_3 \cdot \mathbf{h}'' \cdot \mathbf{n}_3 \]  

(22)

\[ \zeta^{gw} \rightarrow (1/2)L_1(L_3 - L_2) \mathbf{n}_1 \cdot \mathbf{h}'' \cdot \mathbf{n}_1 \]
\[ + (1/2)L_2(L_1 - L_3) \mathbf{n}_2 \cdot \mathbf{h}'' \cdot \mathbf{n}_2 \]
\[ + (1/2)L_3(L_2 - L_1) \mathbf{n}_3 \cdot \mathbf{h}'' \cdot \mathbf{n}_3 \]  

(23)

\[ X^{gw} \rightarrow -2L_2L_3 \mathbf{n}_2 \cdot \mathbf{h}'' \cdot \mathbf{n}_2 \]
\[ + 2L_2L_3 \mathbf{n}_3 \cdot \mathbf{h}'' \cdot \mathbf{n}_3 \]  

(24)

\[ P^{gw} \rightarrow L_1(L_3 - L_2) \mathbf{n}_1 \cdot \mathbf{h}'' \cdot \mathbf{n}_1 \]
\[ + L_2L_1 \mathbf{n}_2 \cdot \mathbf{h}'' \cdot \mathbf{n}_2 \]
\[ - L_3L_1 \mathbf{n}_3 \cdot \mathbf{h}'' \cdot \mathbf{n}_3 \]  

(25)

\[ E^{gw} \rightarrow L_1(L_2 - L_3) \mathbf{n}_1 \cdot \mathbf{h}'' \cdot \mathbf{n}_1 \]
\[ - L_1L_2 \mathbf{n}_2 \cdot \mathbf{h}'' \cdot \mathbf{n}_2 \]
\[ + L_1L_3 \mathbf{n}_3 \cdot \mathbf{h}'' \cdot \mathbf{n}_3 \]  

(26)

\[ U^{gw} \rightarrow - L_1(L_2 + L_3) \mathbf{n}_1 \cdot \mathbf{h}'' \cdot \mathbf{n}_1 \]
\[ + L_1L_2 \mathbf{n}_2 \cdot \mathbf{h}'' \cdot \mathbf{n}_2 \]
\[ + L_1L_3 \mathbf{n}_3 \cdot \mathbf{h}'' \cdot \mathbf{n}_3 \]  

(27)
equilateral triangle, $L = 16.67$ seconds
equilateral triangle, L = 16.67 seconds
equilateral triangle, $L = 16.67$ seconds
**Procedure: Noises**

- Spectra of individual proof-mass noise and single optical path noise (mostly shot + beam pointing) from the LISA Pre-Phase A report—these are expressed in units of length per square-root-Hz

- Square to get power spectra, convert from units of length^2/Hz to fractional Doppler (derivative theorem for Fourier transforms) to get equivalent velocity spectrum and divide by speed of light squared to convert to spectrum of y: $S_{\text{proof mass}}$ and $S_{\text{optical path}}$

- Write the noise-canceling data combination under consideration in terms of the defining $y_{ij}$'s. Square of Fourier-transform gives noise spectrum transfer functions multiplying $S_{\text{proof mass}}$ and $S_{\text{optical path}}$.

- Examples: Aggregate noise spectrum for data combinations X, P, etc. in equilateral and non-equilateral triangle cases
equilateral triangle, $L = 16.67$ seconds
SNR = 5, \( \tau = 1 \) year, generalized combination X

equilateral triangle, \( L = 16.67 \) seconds

Using Estabrook, Tinto, Armstrong (2000) transfer functions with:

- acceleration: \( 3E-15 \) (m/sec**2)/sqrt(Hz) for each proof mass
- shot+pointing: \( 20E-12 \) m/sqrt(Hz)
sensitivity for SNR = 5, $\tau = 1$ year
equilateral triangle, $L = 16.67$ seconds
sensitivity for SNR = 5, $\tau = 1$ year

equilateral triangle, $L = 50.01$ sec (i.e., 3X nominal)
sensitivity for SNR = 5, τ = 1 year
equilateral triangle, L = 5.557 sec (i.e., 1/3 nominal)
sensitivity for SNR = 5, $\tau = 1$ year

equilateral triangle, $L = 1.667$ sec (i.e., $1/10$ nominal)
Application of TDI: On-Orbit Noise Calibration and Isolation of GW Background

• Different TDI combinations have different coupling to GWs

• In particular, the "symmetrical Sagnac" combination, ζ, is in the equal-armlength case insensitive to GWs but contains the noises from all the links

• ζ allows on-orbit and continuous calibration of the noises

• Comparison of ζ with a more GW-sensitive TDI combination (e.g. X) allows unambiguous isolation of a confusion-limited GW background from instrumental noise


• C. Hogan and P. Bender, Phys. Rev. D, 64, 062002 (2001) have proposed a technique for improving LISA’s sensitivity to backgrounds by weighted combinations of the spectra of X, Y, Z, and ζ
sensitivity for SNR = 5, \( \tau = 1 \) year

equilateral triangle, \( L = 16.67 \) seconds
Practical Problems

• In actual LISA detector, lasers will not have the same center frequencies and the spacecraft have relative motion

• Laser center frequency offsets + systematic Doppler drifts due to the orbits now bring in noise from the USO’s used in the downconversion of the photodetector fringe rates
  • Optical bench noise no longer cancels exactly

• Flyable USO’s have fractional frequency deviations $\sim 10^{-13}$ in the LISA band—if uncorrected, these would introduce unacceptable noise (orders of magnitude larger than the LISA design sensitivity)

• Modulation of the main laser signals with the USO signals gives additional calibration data which can correct for this to acceptable levels (Hellings, Danzmann et al. Optics Comm. 124, 313 (1996); Tinto, Estabrook, Armstrong Phys. Rev. D. 65, 082003 (2002).)
Summary

• LISA can be analyzed symmetrically in terms of Doppler shifts on 6 one-way laser links connecting 6 optical benches on the three spacecraft.

• Time-delay interferometry provides many ways—not just Michelson—to combine these links with appropriate time delays, canceling principal noises even with unequal and time-varying arms.

• Provides a framework for analysis of signals, noises, sensitivity, and some design tradeoffs (e.g. Doppler shifts due to orbits, USO stability, offsets in laser center frequencies)

• Results valid across the whole LISA band, not just in the LWL

• Multiple noise-canceling data streams can be formed simultaneously
  • Differing sensitivity to GWs can be exploited—e.g. TDI-combination ζ for assessing on-orbit instrumental noise and isolating it from GW background
  • Robustness against some classes of subsystem failure—e.g. the 4-link combinations (X, Y, Z), (E, F, G), (P, Q, R), (U, V, W)
  • Design for specific waveforms
  • Discriminate signals and noises based on differing transfer functions